Machine Learning for NLP Bonus lecture: The averaged perceptron



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overview

- ▶ a simple modification of the perceptron algorithm
- ▶ often gives quite nice improvements in practice



perceptron pseudocode

```
\mathbf{w} = (0, \dots, 0)

repeat N times

for (\mathbf{x}_i, \mathbf{y}_i) in training set \mathcal{T}

score = \mathbf{y} \cdot \mathbf{w} \cdot \mathbf{x}_i

if score \leq 0

\mathbf{w} = \mathbf{w} + \mathbf{y} \cdot \mathbf{x}

return \mathbf{w}
```



a problem with the perceptron?

- we return the most recent version of the weight vector
- intuitively, this version is over-adapted to the last few instances, and may work less well for other instances



intuition: combining classifiers by voting or averaging

- let's assume we have a lot of classifiers
- each of them has its own strengths and weaknesses
- could they somehow work together?
 - voting: return the output favored by most of the classifiers
 - averaging: compute the prediction scores for all classifiers; return the output selected by considering the average of all the scores



using averaging to handle the overfitting problem

- ▶ in the perceptron, each version of the weight vector can be seen as a separate classifier
 - so we have $N \cdot |\mathcal{T}|$ classifiers
- each of them is over-adapted to the last examples it saw
- but if we compute their average, then maybe we get something that works better overall?
- averaged perceptron: return the average of all versions of the weight vector





averaged perceptron pseudocode (naive)

```
\mathbf{w}_0 = (0, \dots, 0)
t = 0
repeat N times
    for (x_i, y_i) in training set \mathcal{T}
         score = y \cdot \mathbf{w}_t \cdot \mathbf{x}_i
         if score < 0
              \mathbf{w}_{t+1} = \mathbf{w}_t + y_i \cdot \mathbf{x}_i
         else
              w_{t+1} = w_t
         t = t + 1
return \frac{\mathbf{w}_1 + \dots + \mathbf{w}_{N \cdot |\mathcal{T}|}}{N \cdot |\mathcal{T}|}
```



this is too impractical!

- ▶ it's a waste of memory to remember all the versions of w that we have used during training
- can we do something smarter?

an observation

 \blacktriangleright the weight vector \mathbf{w}_3 is the sum of all updates so far:

the average of three vectors can be written:

$$\frac{\mathbf{w}_1 + \mathbf{w}_2 + \mathbf{w}_3}{3} = \frac{\Delta_1}{3} + \frac{\Delta_1 + \Delta_2}{3} + \frac{\Delta_1 + \Delta_2 + \Delta_3}{3}$$
$$= \frac{3}{3}\Delta_1 + \frac{2}{3}\Delta_2 + \frac{1}{3}\Delta_3$$

better averaged perceptron

```
\mathbf{w} = (0, \ldots, 0)
a = (0, ..., 0)
step = N \cdot |\mathcal{T}|
repeat N times
    for (x_i, y_i) in training set \mathcal{T}
        score = y_i \cdot \mathbf{w} \cdot \mathbf{x}_i
        if score < 0
             \mathbf{w} = \mathbf{w} + \mathbf{y}_i \cdot \mathbf{x}_i
            a = a + \frac{step}{N \cdot |\mathcal{T}|} y_i \cdot x_i
        step = step - 1
return a
```



in Python

```
class AveragedSparsePerceptron(LinearClassifier):
   # ...
   def fit(self, X, Y):
        # ... initialization ...
        w = numpy.zeros( n_features )
        a = numpy.zeros( n_features )
        NT = self.n_iter * len(Y)
        step = NT
        for i in range(self.n_iter):
            for x, y in zip(X, Yn):
                score = sparse_dense_dot(x, w) * y
                if score <= 0:
                    add_sparse_to_dense(x, w, float(y))
                    add_sparse_to_dense(x, a, step * float(y) / NT)
                step -= 1
        self.w = a
```



experiment (assignment 2 dataset)

- standard: training time 3.4 sec, accuracy 0.809
- ▶ averaged: training time 3.6 sec, accuracy 0.829



