Machine Learning for NLP Lecture 6: Kernel-based classifiers



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overview

 kernels give us an interesting connection between linear and example-based classifiers

- a linear classifier computes a score for each feature, and then sums the scores
- an example-based classifier uses a similarity function to compare a new instance to the training examples
- informally, kernels are similarity functions; formally, they are dot products in some transformed vector space
- we start from the linear classifiers and show that many of them have an alternative example-based form
- the selling point: get rid of feature engineering, use a similarity function instead





the primal and dual forms

mapping feature vectors into higher-dimensional spaces

kernels in classifiers





the primal and dual forms of a linear classifier

the primal form of a linear classifier is the one that we have seen so far, where the classifier is defined in terms of features:

$$\mathsf{score}(oldsymbol{x}) = oldsymbol{w} \cdot oldsymbol{x}$$

▶ in the dual form, we instead state the scoring function in terms of the training examples X = x₁,..., x_n:

$$\operatorname{score}(\mathbf{x}) = \sum_{i} \alpha_{i} \cdot (\mathbf{x}_{i} \cdot \mathbf{x})$$

where α_i is an importance weight for the training example x_i

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the primal and dual forms: reflection

primal dual
score(x) = w · x score(x) =
$$\sum_{i} \alpha_{i} \cdot (x_{i} \cdot x)$$

- the dual form can be seen as some sort of example-based classifier
- why do we say that the primal and the dual are related?

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can we go from the dual to the primal?

the primal and dual forms: reflection

primal
score(x) =
$$\mathbf{w} \cdot \mathbf{x}$$
 score(x) = $\sum_{i} \alpha_{i} \cdot (\mathbf{x}_{i} \cdot \mathbf{x})$

- the dual form can be seen as some sort of example-based classifier
- why do we say that the primal and the dual are related?
 - can we go from the dual to the primal?

$$\boldsymbol{w} = \sum_{i} \alpha_{i} \cdot \boldsymbol{x}_{i}$$

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it's not obvious that we could make the opposite conversion...



perceptron in the primal and dual forms

```
initialize to all zeros:
  primal: w = (0, ..., 0)
  dual: ?
for (x_i, y_i) in the training set (X, Y)
  if y_i is positive and score(x_i) <= 0
    add x_i to the classifier
       primal: w = w + x_i
       dual: ?
  else if y_i is negative and score(x_i) >= 0
    subtract x_i from the classifier
       primal: w = w - x_i
       dual ?
return the classifier
```

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perceptron in the primal and dual forms

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initialize to all zeros:
  primal: w = (0, ..., 0)
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perceptron in the primal and dual forms

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  primal: w = (0, ..., 0)
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for (x_i, y_i) in the training set (X, Y)
  if y_i is positive and score(x_i) <= 0
     add x_i to the classifier
        primal: w = w + x_i
        dual: \alpha_i = \alpha_i + 1
  else if y_i is negative and score(x_i) >= 0
     subtract x_i from the classifier
        primal: w = w - x_i
        dual: \alpha_i = \alpha_i - 1
return the classifier
```

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what about the SVM?

 recall that the SVM can be defined in terms of a few support vectors



- this shows how the classifier is determined by the examples
- \blacktriangleright for the support examples, the lpha's are non-zero





the representer theorem

the representer theorem shows that

if the learning method is stated as a minimization of

$$objective(w) = regularizer(w) + loss(w)$$

then the solution can be written in the dual form:

$$\boldsymbol{w} = \sum_{i} lpha_{i} \cdot \boldsymbol{x}_{i}$$

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- this class of learning methods includes SVM and LR
- Schölkopf, Herbrich, and Smola (2001): A generalized representer theorem





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mapping feature vectors into higher-dimensional spaces

kernels in classifiers





recap: linear separability

some datasets can't be modeled with a linear classifier!



➤ a dataset is linearly separable if there exists a w that gives us perfect classification

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a simple example of linear inseparability: an "XOR" situation

very good	Positive
very bad	Negative
not good	Negative
not bad	Positive



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mapping into a larger vector space

we may add "useful combinations" of features to make the dataset separable:

very good very-	good Positive
<i>very bad</i> very-l	bad Negative
<i>not good</i> not-g	ood Negative
<i>not bad</i> not-b	ad Positive

from a geometrical viewpoint: we are creating a feature space with a higher dimensionality:



• lots of features \rightarrow LOTS of combinations

mapping into a new vector space: formally

- ▶ we have some function ϕ that will take a feature vector x and convert it into a higher-dimensional vector $\phi(x)$
 - typically by forming combinations of the parts of x
- ▶ then, instead of training a classifier on X = x₁,..., x_n, we train it on φ(X) = φ(x₁),..., φ(x_n)
- ▶ it seems like a problem that φ would give a vector with a huge dimensionality, but we'll show later that we don't need to compute φ explicitly

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```
example: XOR dataset
```

```
clf = LinearSVC()
clf.fit(X, Y)
```

linear inseparability, so we get less than 100% accuracy
print(accuracy_score(Y, clf.predict(X)))



example: XOR dataset converted into 3 dimensions

let's apply the function

```
\phi([x1, x2]) = [x1^2, x2^2, \sqrt{2} \cdot x1 \cdot x2]
X = numpy.array([[1, 1, sqrt(2)*1*1]],
                   [1, 0, sqrt(2)*1*0],
                   [0, 1, sqrt(2)*0*1],
                   [0, 0, sqrt(2)*0*0]])
Y = ['no', 'yes', 'yes', 'no']
clf = LinearSVC()
clf.fit(X, Y)
# in the 3-dimensional space, we get 100% accuracy
```

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print(accuracy_score(Y, clf.predict(X)))





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let's combine the two ideas we've been discussing:

- converting examples x into higher-dimensional vectors $\phi(x)$
- using the dual form of the classifiers

then we get:

$$\operatorname{score}(\mathbf{x}) = \sum_{i} \alpha_{i} \cdot (\phi(\mathbf{x}_{i}) \cdot \phi(\mathbf{x}))$$

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• we mentioned previously that it seems like a problem that $\phi(\mathbf{x})$ is huge...



the "kernel trick"

▶ in the dual form, the feature vectors φ(x)₁,..., φ(x)_n are used in dot products only:

$$\operatorname{score}(\mathbf{x}) = \sum_{i} \alpha_{i} \cdot (\phi(\mathbf{x})_{i} \cdot \phi(\mathbf{x}))$$

a kernel K is a function that corresponds to a dot product in some transformed vector space

$$\mathsf{score}(\mathbf{x}) = \sum_i \alpha_i \cdot \mathcal{K}(\mathbf{x}_i, \mathbf{x})$$

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► the "kernel trick": in some cases, we may compute the kernel without actually computing φ

example: quadratic kernel

recall the previous example, where we had

$$\phi([x_1, x_2]) = [x_1^2, x_2^2, \sqrt{2} \cdot x_1 \cdot x_2]$$

in this case, we can compute the high-dimensional dot product without actually making the high-dimensional vectors:

$$K(\boldsymbol{a}, \boldsymbol{b}) = \phi(\boldsymbol{a}) \cdot \phi(\boldsymbol{b}) = (\boldsymbol{a} \cdot \boldsymbol{b})^2$$

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this is called a quadratic kernel



quadratic kernel: derivation

$$\phi([a_1, a_2]) \cdot \phi([b_1, b_2]) = [a_1^2, a_2^2, \sqrt{2}a_1a_2] \cdot [b_1^2, b_2^2, \sqrt{2}b_1b_2] =$$
$$= a_1^2b_1^2 + a_2^2b_2^2 + 2a_1a_2b_1b_2 =$$
$$= (a_1b_1 + a_2b_2)^2 =$$
$$= ([a_1, a_2] \cdot [b_1, b_2])^2$$

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some common kernels

- many of the commonly used kernels are just some nonlinear function applied to the normal dot product
- ▶ polynomial kernel: $K(a, b) = (a \cdot b + c_0)^d$
 - ... where d is called the **degree** and c_0 the **offset**
 - this category includes the linear and quadratic kernels
 - in general, a polynomial kernel with degree d will implicitly form all combinations of d features

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► **RBF kernel**: $K(a, b) = \exp(-\gamma \cdot |a - b|^2)$



- the classifier sklearn.svm.SVC is an SVM implementation that uses kernels, as opposed to LinearSVC that we saw before
- examples:
 - > quadratic: SVC(kernel='poly', degree=2)
 - RBF: SVC(kernel='rbf')

> you can also use your own kernel, instead of one of the built-in

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SVC(kernel=my_kernel_function)



example: XOR dataset with quadratic-kernel SVM

we get 100% accuracy because the quadratic kernel
implicitly works in the 3-dimensional space

```
print(accuracy_score(Y, clf.predict(X)))
```



decision boundaries: linear and quadratic SVM

- a kernel-based classifier is linear in the high-dimensional space, but non-linear in the original space
- example: linear SVM compared to SVM with quadratic kernel





kernels as similarity functions

- \blacktriangleright by using a kernel, we got rid of the feature transformation ϕ
- we can dispose of the feature extraction step as well!
- in that case, the kernel function K(a, b) becomes a similarity function between two objects a and b
- some interesting kernels useful in NLP:
 - string kernels: how many substrings do the two strings have in common?

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- tree kernels: how many subtrees do the two trees have in common?
 - many papers by Moschitti on this topic
- graph kernels
- lexicon-based similarity functions, for instance with WordNet



kernels in practice

- as we discussed, a kernel-based classifier can be seen as an example-based classifer
 - so they share the weakness of being slow at test time
 - as the training set grows, the classifier becomes slower...
- when should we use a kernel?
 - when defining a similarity function is easier than coming up with features
 - or when we think the features interact in some complicated way

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 the alternative: extract features as normal, try to use your intuition and form feature combinations manually or by trial and error

